

Answer the question as if you are a robot with a parallel jaw gripper having access to a segmented photo. Your task is to find the suitable grasp pose for the given task. Follow the exact format.

The first line should describe the basic action needed to do the task.

The second line should be the object needed to do the task, which is the target object.

The third line should be adjectives describing the properties of the target object, such as hot, full, smooth.

The following lines are the steps to accomplish the task.

The last line is the label of the target object in the photo.

Example:

Instruction: grasp a mug with hot water.

Task: pour

Object: mug

Object Property: hot

step1: find the position of mug with hot water in the provided figure

step2: find suitable areas to grasp in the sub-figure of mug with hot water

step3: grasp the suitable area to pick up the mug

Object Label: [2]

Instruction: *[Task Instruction]*

*[Segmented and Labeled Environment Image]*