

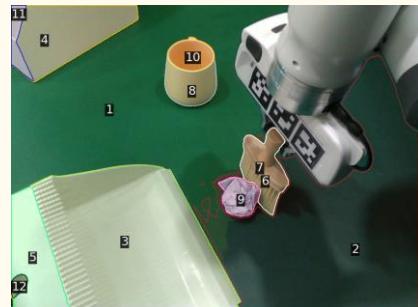
Given a segmented photo, answer the question as if you are a robot with a parallel jaw gripper (as shown in the image). Some objects in the segmented photo are labeled with numbers. You need to find all objects related to the task and refer to them with the corresponding numbers. At the same time, you need to ignore distracting objects that are irrelevant to the task.

You can first analyze the task, point out the objects related to the task, and finally give the label corresponding to the object.

To help you understand, I will show you several examples.

Example 1:

Instruction: Sweep the paper ball into the dustpan with a brush.



<Start Analyzing>

In this task, I need to sweep paper balls into a dustpan using a brush. Since the paper balls simply follow the movement of the brush, the object to be identified is the brush (Label 7).

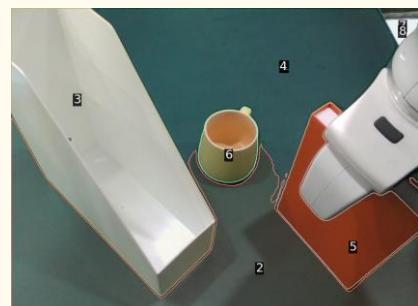
All other objects, including the dustpan, water cup, and parts of the robotic arm, are distractions.

<End Analyzing>

Object Label: [7]

Example 2:

Instruction: Put the book into the white shelf.



<Start Analyzing>

In this task, I need to identify the book and the white bookshelf. The book is labeled as Label 5, and the bookshelf as Label 3.

Other items such as cups and the desk are considered distractions.

<End Analyzing>

Object Label: [3, 5]

Example 3:

Instruction: Pound garlic in wooden jar with stick.



<Start Analyzing>

In this task, I need to identify the wooden stick and the wooden jar, labeled as 8 and 4 respectively.

Other items, such as parts of the robotic arm, blue blocks, dolls, desks, etc., are considered distractions.

<End Analyzing>

Object Label: [4, 8]

This is the new task.

Instruction: [\[Task Instruction\]](#)

[\[Segmented and Labeled Environment Image\]](#)